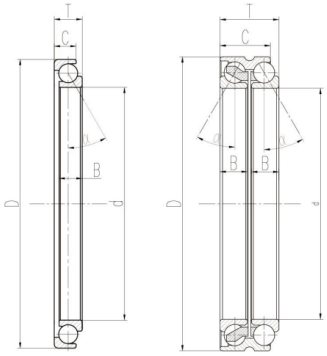
三立机器人技术
SANLI ROBOT TECHNOLOGY





Désignation	Dimensions principales (mm)					Charges nominales de base	
	d	D	B	C	T	Dynamique	Statique
d90L	90	□	10	□	□	24.8	28
d160	160	□	26.5	□	□	101.1	124.9
d240	240	□	24.1	□	□	209.6	290.5
SE140	110	140	15	12	16	31.2	36.3
SE140/YA	110	140	15	12	16	35.5	44.1
SE170	136	170	13	13	19.5	31.2	39.1
SE18D	145	180	20	19	21	56.1	72.5
SE185	145	185	22	20	22	41.4	52.5
SE195	155	195	15	15	20	65.1	86.9
SE210	165	210	16.8	19	22	724	98
SE225	180	225	16.5	18	21.5	74.6	105
SE235	180	235	20.9	25	26.3	117.5	154.5
SE250	200	250	23	20.5	24	168	285
SE276	220	276	18	26	26	114.5	164
SE295	220	295	25.5	25.5	33	201.1	265.9
SE310	230	310	27	27	38	214	290
SE313	246	313	22	22	32	180	270
SE330	250	330	27	27	38	212.8	299
SE360	250	360	36	34	44	319.5	467
SE370	280	370	27	22	40	228.7	335.9

SE400	280	400	39	37	48	365.5	575.2
SE402	304.8	402	50.8	38	50.8	305	488
SE420	280	420	37	37	48	385.5	618.3
SE423	330	423	50	38	50	294	480
AC130166	130	166	4	14	18	52.5	68.4
AC135170	135	170	15	20	20	53.9	71.7
AC150182	150	182	12	16	16	47.3	65.4
AC220300	220	300	28	28	35	206.1	270.6
AC300370	300	370	28.5	28.5	33	209.8	320.4
DE166	130	166	12X2	30.5	35.5	72.1	114.4